

# X-Pro Speedcontroller



Dear Customer,

Thank you for your purchase of the **X- Pro-Series Controller**, a new generation of sensorless speed controllers especially for '**Hacker Brushless A-Series- Motors**' and other Brushless Motor Designs. Special programming options are provided to ensure the best possible power and performance from your motor system. '**Brushless**' systems offer high power efficiency combined with low weight and compact dimensions. For best performance and reliability from your Controller, use only High quality connectors, motors and batteries.

**Please, pay careful attention to the following instructions before you start to work with your new motor and speed controller.**

## **Connections:**

The speed controller can be connected to the motor by direct soldering or with high quality connectors. Always use new connectors, which should be soldered carefully to the cables and insulated with Heat-shrink tubing. It is possible to extend the cables to the motor battery pack up to a maximum of 8 inches. Deans Ultra or other high quality connectors are recommended for connecting the motor battery pack to the controller.

- **Solder Controller to the Motor wires**
- **Solder appropriate connectors to the Battery wires**
- **Insulate all Solder connections with Heat Shrink Tubing.**
- **Plug the JR connector into the receiver throttle channel.**

When connecting controller to battery pack, care should be taken to ensure that multiple touches of the connectors are not made.

Reversing the motor directions is achieved by the exchanging the position of any two wires connected to the motor or by programming "rotation reverse".

## **Installing the Controller:**

Install the speed controller in the model so that it is isolated from vibration and shock, using Velcro or double sided foam tape. Allow space around it for cooling. Make sure that there is sufficient cooling of the motor and speed controller by ducting air through adequate cooling holes from the outside airflow. Main power packs should be connected at one attempt.

The X-speed controllers have an optimal default setup for A-Motors.

### **Factory default settings:**

Brake: **Off**

Battery type all ESCs: **Li-Po**

Cut off: **LiPo-Autodetect with 3,2V/cell (Pack must have more than 3,8V/cell while connected, in other case, the ESC cannot detect the correct Nr. of cells and this may cause a underloaded Pack)**

Under voltage: **Reduce power**

Acceleration : **Fast**

Timing: **Auto**

Frequency: **8KHz**

Active RPM-Control (Helimode / Governormode): **Off**

### **Normal start up:**

When throttle stick is off, connect battery pack, switch on the controller (if switch is installed), you will hear a number of tones which indicate the number of cells the ESC detected and two tones for Brake off.

For changing the default setup, please read the following manual

### **ESC program procedure**

#### **It is possible to program the ESC in two different ways:**

-by using a Computer with "Hacker X-Pro USB-Interface" and a special software, which can be acquired, (see then enclosed operating instructions).

The USB software offers still additional adjusting parameters:

- variable cutoff voltage for LiPo cells
- Brake "off", "soft", "hard"
- finer gradations in the Motortiming
- acceleration in three stages selectable
- updates for the X-Pro ESC

-programming by throttlestick:

With throttle stick at full power, connect the battery and wait for 5 sec. Program mode is entered when you hear two low tones and two high tones. \_\_ - -

Each time you enter the programming mode you are allowed to make one change and then you will automatically exit the programming mode. To change more than one parameter you will have to re-enter the programming mode each time.

**Attention!** LiPo-Autodetect is the factory-default-setting. It can be deactivated with throttle-stick programming but can only activated by programming with PC-Software and USB!

#### **1. Brake**

To change the brake function, as soon as you hear the programming tones mentioned above, move the throttle stick to low position. **Brake** function will be inverted. (IE: If brake was on, it now will be off.)

To change any of the remaining functions, enter the programming mode as detailed above. Leave the throttle at high position until you are within the five sets of beeps as detailed in

each of the choices below. When you arrive at the choice you want to make, move the throttle to low position while that series of 5 tones are still being heard.

WARNING: the motor will run now by moving the throttlestick!

## 2. Battery type

(Voltage Cut-off)

NiCd: . . . . .

2 Lipos: (5.8V) .. .. .

3 Lipos: (8.7V) ... .. .

4 Lipos: (11.6V) .... .. .

5 Lipos: (14.5V) ..... .. .

6 Lipos: (17.4V) ..... .. .

Following cell-setting only available in OPTO-Versions

7 Lipos: (20.3V) ..... .. .

8 Lipos: (23.2V) ..... .. .

9 Lipos: (26.1V) ..... .. .

10 Lipos: (29.0V) ..... .. .

## 3. Under voltage

reduces power when the battery gets low. -\_ -\_ -\_ -\_ -\_

cuts off power when the battery getslow. \_- \_- \_- \_- \_-

## 4. Acceleration

Low: V V V V V

Medium: VV VV VV VV VV

High: VVV VVV VVV VVV VVV

## 5. Timing

Automatic: (7 ~ 30 degree) (recommended) - - - - -

Soft: (7 degree) (2-pole motors) -- -- -- -- --

Hard (22 ~ 30 degree) (multipole motors) --- --- --- --- ---

## 6. Frequency

8 kHz: (recommended) \ \ \ \ \

16 kHz / / / / /

## 7. Rotation reverse

Reverse motor rotation            W W W W W

## 8. Active RPM-Control, Heli-/ Governormode

rpm control: **Off**                    -·-   -·-   -·-   -·-   -·-  
up to 20 000 electrical RPM:    -··-   -··-   -··-   -··-   -··-  
up to 50 000 electrical RPM:   -···-   -···-   -···-   -···-   -···-  
above 50 000 electrical RPM:   -····-   -····-   -····-   -····-   -····-

(electrical RPM on two-pol motors, for a 4-pol motor for example:  
50 000 electrical RPM:2 = 25 000RPM, 10-pol motors electrical 50 000RPM:5  
= 10 000RPM and so on...)

### Trouble shooting:

- Switch “ON” the transmitter and check the throttle channel settings are +/-100% (for computer radios). For Futaba Radios program the “Servo Reverse” function on the throttle channel. **Set the throttle to “closed” or brake position**
  - Locate the controller to Avoid multiple touches of the connectors when installing a fresh motor battery pack
  - You must hear a ‘beep’. **Between switching on the switch and the ‘beep’ the throttle stick must not be moved.** If you do not hear a ‘beep’, switch off the switch, disconnect the power connectors, wait for 5 seconds and repeat the procedure of connecting and switching on.
  - If you do not hear ‘beep’ again, check the following:
    - - Is JR connector plugged in throttle channel?
    - - Is the throttle stick in “closed” position (OFF)?
    - - Is the throttle channel in ‘normal’ position? (for Futaba, in the Reverse position?)
  - The position of ‘full throttle’ will be adjusted automatically
  - All programming will be stored.
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- The speed controller will turn-off the motor when the main power pack voltage falls under 5,5 V or at the voltage which is programmed in step “under voltage”. It depends on which occurs first.
  - Temperature overload protection is built into the speed controller; it turns off the motor when the temperature reaches 230° F /110° C.
  - These speed controllers are equipped with protection functions that take care of correct start and operation of the motor across the whole range of RPM, Current and Voltage.
  - **Do Not connect the speed controller to just ‘any’ kind of power source.** Take care to ensure the right polarity of NiCd/ NiMH or LiPoly power packs only.
  - **Do not connect the motor battery to the wrong polarity; the speed controller will be severely damaged.**
  - **Controllers connected to the wrong battery polarity, WILL NOT be covered under the warranty**

# Warranty Terms and Conditions

Hacker Brushless Motors warrants products to be free from defects at the date of purchase. This warranty does not cover any component parts damaged by use or modification. Hacker Brushless Motors reserves the right to change or modify this warranty without notice.

In that Hacker Brushless Motors has no control over the final assembly, no liability shall be assumed nor accepted for any damage resulting from the use by user of the final assembled product, the user accepts all resulting liability.

All returns require a "Merchandise Return Authorization (MRA)", which can be obtained by contacting Hacker Brushless Motors. No returns of any type will be accepted without a MRA number and will be returned to the sender. The following information is required for obtaining a MRA number: Customer name (or Store name), Invoice number, part or model number and explanation of defect or problem.

- Hacker Brushless Motors must authorize all returns within 7 days from receipt of order
- All returns must have a copy of the original invoice with MRA number
- All returning packages must have the MRA number clearly marked on the outside of the packaging
- All packages shall be inspected upon delivery. All claims for damaged products must be made with carrier within 3 days of the receipt of the package.
- All defective items must be processed through the Manufacturer or the Distributor of the product
- Sender must prepay all transportation and insurance charges
- All returning items must be in new, saleable condition. They must have original packing material, manuals and accessories

- **Warning: Once the Motor Battery Pack is connected, handle the model with extreme care!** Ensure that you are well clear of the propeller at all times. Rotating propellers are extremely dangerous!
- Always Connect the motor battery pack just before flight and disconnect it immediately after landing the model.
- **Warning: Even when the switch is 'off' remember the Motor Battery pack may be connected, handle the model with extreme care and stay well clear of the Propeller!**

## **Declaration of conformity**

The described products are in compliance with the relevant and applicable EC guidelines for electromagnetic compatibility:

89/336/EWG

92/31/EWG

93/68/EWG

Many happy landings!

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